

A New Class of Multivariate Prior Distributions with an Application to Reliability Engineering

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Bayesian decision framework

Bayesian framework

- Let X be the underlying observation with PDF $f_{\theta}(x)$.
- θ represents the unknown parameter.
- Θ the set of states, $\theta \in \Theta \subseteq \mathbb{R}^n$, $n \in \mathbb{N}$, $n \geq 1$.
- Let π be the **specific prior state of knowledge** over Θ with PDF $\pi(\theta)$.
- Let $\pi_{\mathbf{x}}$ be the **posterior state of knowledge** after observing data, \mathbf{x} , with PDF given by

$$\pi_{\mathbf{x}}(\theta) = \frac{l(\theta | \mathbf{x})\pi(\theta)}{m_{\pi}(\mathbf{x})},$$

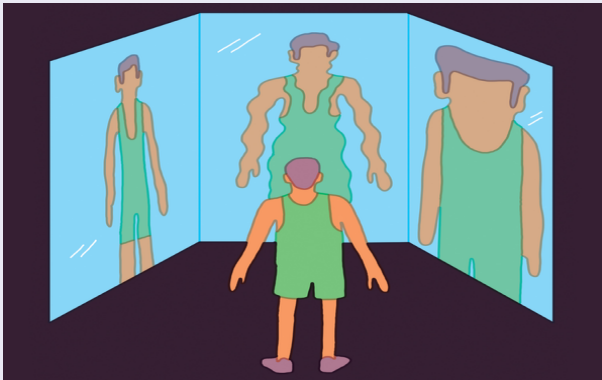
where $l(\theta | \mathbf{x})$ and $m_{\pi}(\mathbf{x})$ denote the likelihood function and the marginal density, respectively.

- **OBJECTIVE:** To make inference in some quantity of interest by using $\pi_{\mathbf{x}}$.

Bayesian sensitivity

The classical criticism

Why a unique prior? A Bayesian analysis is robust if it does not depend sensitively on the initial assumptions -Bayesian sensitivity-.



- **A solution.** Beliefs will be modelled by a particular class of priors Γ .

An invitation to see our research

HEY, YOU!!

I hope to see you and tell you all details!!!